

**R16**

Code No: 136BE

JAWAHARLAL NEHRU TECHNOLOGICAL UNIVERSITY HYDERABAD

B. Tech III Year II Semester Examinations, March - 2024

**DIGITAL SIGNAL PROCESSING**  
(Electronics and Communication Engineering)

Time: 3 Hours

Max. Marks: 75

**Note:** i) Question paper consists of Part A, Part B.

ii) Part A is compulsory, which carries 25 marks. In Part A, Answer all questions.

iii) In Part B, Answer any one question from each unit. Each question carries 10 marks and may have a, b as sub questions.

**PART - A**

**(25 Marks)**

- 1.a) Determine the fundamental period of the signal  $x(n) = \cos\left(\frac{60\pi n}{110}\right)$ . [2]
- b) Outline Parseval's relation in Z-transform. [3]
- c) State the property of Circular Shift of a Sequence in DFT. [2]
- d) State the difference between DIT and DIF algorithms. [3]
- e) How is the order of a Butterworth filter required to achieve a certain stopband attenuation determined? [2]
- f) What is meant by Warping effect and how can it be eliminated? [3]
- g) What are the desirable characteristics of a Window? [2]
- h) Discuss situations where FIR filters are preferred over IIR filters, and vice versa. [3]
- i) Define upsampling and interpolation and explain their relationship. [2]
- j) What are the strategies for optimizing filter design to achieve the desired balance between round-off and overflow noise? [3]

**PART - B**

**(50 Marks)**

- 2.a) Find the output response of the discrete time system described by the following difference equation  
 $y(n) - 0.86y(n-1) + 0.186y(n-2) = x(n)$  where  $x(n) = \left(\frac{8}{9}\right)^n u(n)$  subjected to the initial conditions  $y(-1) = 1$  and  $y(-2) = 2$ . Also find out the step response.
- b) For the following discrete time signals, determine whether or not the system is linear, shift invariant, causal and stable
  - i)  $y(n) = \sinh[nx(n) + x(n+5)]$
  - ii)  $y(n) = x(-n-7)$[5+5]

**OR**

- 3.a) Solve for  $x(\infty)$ , if  $X(Z)$  is given by  
$$\frac{z}{z+4}$$
$$\frac{8(z^2-1)(z+0.7)}{z+4}$$
- b) Determine the system function  $H(z)$ , impulse response  $h(n)$ , magnitude response and phase response of the LSI system  $y(n) = x(n) + 3x(n-1) + 2y(n-1) - y(n-2)$ . [3+7]

4.a) Given a sequence  $x[n] = \{1, 2, 3, 4, 5\}$  and a length  $N = 3$ , compute its DFT using the Over-Lap Save method.

b) For a given discrete-time signal  $x[n]$  and its Z-transform  $X(z)$ , express the relationship between DTFT, DFS, DFT, and Z-Transform for this signal. [5+5]

**OR**

5.a) The 8-point DFT of the sequence  $x(n) = \left\{ \frac{1}{\sqrt{2}}, 1, \frac{1}{\sqrt{2}}, 0, -\frac{1}{\sqrt{2}}, -1, -\frac{1}{\sqrt{2}}, 0 \right\}$ . Solve the DFT of the sequence using DIT-FFT algorithm.

b) Evaluate the IDFT of the sequence  $X(K) = \{1, 1 + j, 2, 1 - 2j, 0, 1 + 2j, 0, 1 + j\}$  [5+5]

6.a) Design a digital Chebyshev low pass filter satisfying the following specifications.

$$0.707 \leq |H(e^{j\omega})| \leq 1.0, 0 \leq \omega \leq 0.4\pi$$

$$|H(e^{j\omega})| \leq 0.2, 0.6 \leq \omega \leq \pi \text{ with } T = 1 \text{ sec}$$

Using Bilinear transformation method.

b) Discuss the transformations relating low pass filter to HPF, BPF and BRF in Digital domain with necessary equations. [5+5]

**OR**

7.a) Design a Band pass Butterworth filter with sampling frequency  $F = 7\text{KHz}$ ,  $\alpha_p = 3\text{dB}$  in the passband  $800\text{Hz} \leq f \leq 1000\text{Hz}$ ,  $\alpha_s = 40\text{dB}$  in the stopband  $4000\text{Hz} \leq f \leq \infty$

b) Describe the design of Analog Low pass filter using Chebyshev Type-I filter with necessary equations. [5+5]

8.a) Explain the steps involved in designing an FIR filter using the frequency sampling technique.

b) Design an ideal differentiator with frequency response.

$$H(e^{j\omega}) = j\omega; -\pi \leq \omega \leq \pi$$

Using hamming window with  $N=11$ .

[5+5]

**OR**

9.a) Discuss the Fourier series method for designing FIR filters. What are its advantages and limitations?

b) Design an FIR low-pass filter with a cutoff frequency of 1000 Hz using the Hanning window function. The filter should have a passband ripple of 0.1 dB and a stopband attenuation of at least 60 dB. Use a sampling frequency of 8000 Hz. [5+5]

10.a) With necessary derivations, explain the operation of sampling rate conversion by a factor of I/D in both frequency and time domains.

b) Explain the concept of polyphase decomposition and its role in bandpass signal conversion. [5+5]

**OR**

11.a) Explain how computational output round-off noise affects the performance of digital filters.

b) Investigate the dead band effects in the implementation of an IIR digital filter with the transfer function  $H(z) = \frac{1}{1 - 0.8z^{-1}}$ . Determine the magnitude of dead band errors introduced by quantizing the filter coefficients to 12 bits and inputs ranging from -2048 to 2047. [5+5]